

Chirol, Clementine, Carr, Simon ORCID: <https://orcid.org/0000-0003-4487-3551>, Spencer, Kate L. and Moeller, Iris (2021) Pore, live root and necromass quantification in complex heterogeneous wetland soils using X-ray computed tomography. *Geoderma*, 387 . p. 114898.

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1 Pore, live root and necromass quantification in
2 complex heterogeneous wetland soils using X-ray
3 Computed Tomography

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6 KEYWORDS: X-ray computed tomography, sediment, microstructure, porosity, live roots,
7 necromass, soil carbon dynamics

8

9 ABSTRACT: Subsurface structures and especially the interactions between pores, roots and other
10 organic matter elements have a strong impact on ecosystem functioning. Yet despite recent
11 progress in the application of X-ray Computed Microtomography (μ CT) to soil structure in
12 agricultural science, applications to the more complex and heterogeneous substrates found in
13 natural soils, specifically wetland soils, remain sparse. We apply X-ray μ CT to a complex
14 heterogenous soil and develop a robust segmentation method to quantify the pores, live roots and
15 necromass. This approach significantly improves the detection of the organic matter elements, and
16 gives us unprecedented detail and resolution in the segmentation of pores, live roots and necromass
17 at a high spatial resolution (62.5 μ m in this study). We identify several situations where pores and

18 organic matter interact in the soil, including the disconnected air spaces (aerenchyma) that run
19 within the *Spartina* stem and roots, tubular-shaped pores left behind by decaying roots, and lateral
20 roots deploying within structural fragilities in the sediment. The capacity of X-ray μ CT to
21 distinguish the connected live root system from the necromass opens possibilities for applications
22 to determine key wetland soil functions such as soil cohesivity, soil nutrient exchanges and soil
23 carbon dynamics.

24 **1. Introduction**

25

26 Soils and sediments, formed respectively from the in-situ weathering of a bedrock in association
27 with biogeochemical processes (Lin, 2010) and from the layered deposition of imported particles
28 (Dyer, 1995), both play a critical role for the ecosystems they support. They are a place of
29 exchange of water, gases and other resources, while providing structural support and shelter for
30 dwelling organisms (Rabot et al., 2018). The structure of these subsurface environments, defined
31 as the three-dimensional spatial arrangement of solids regardless of chemical heterogeneity
32 (Rabot et al., 2018; Xiong et al., 2019), results from the unique pedological (soil) and
33 hydrodynamic (sediment) history of each habitat and is dynamic over multiple spatial and
34 temporal scales. Because of this heterogeneity, structural properties (e.g. the measurable
35 components of the soil structure, such as total porosity) are difficult to describe, yet doing so can
36 greatly improve our understanding of ecosystem functions. Structure conditions
37 geomorphological, pedological and ecological functioning (Corenblit et al., 2011; Lin, 2010;
38 Rabot et al., 2018) and soil/sediment mechanics (Fonseca et al., 2013; Keller et al., 2013;
39 Menzies et al., 2016; Phillips et al., 2018; Spagnolo et al., 2016). Structure notably controls the
40 soils' interactions with the surface by providing pathways for gas, water and solute fluxes (Ball,

41 2013; Dale et al., 2019; Gharedaghloo et al., 2018; Pedersen et al., 2015; Spencer et al., 2017;
42 Swanson et al., 2017). Live roots also provide pathways of gas and nutrient exchanges, and play
43 an important role in soil carbon dynamics (Bardgett et al., 2014; Blagodatsky & Smith, 2012;
44 Smith et al., 2003). Due to these combined functions, structure exerts a critical control over
45 soil/sediment fertility and agricultural potential (Naveed et al., 2016; Pöhlitz et al., 2018; Rogers
46 et al., 2016).

47 Because of the complexity of soil and sediment structure, its influence on ecosystem processes
48 cannot be accurately predicted by one-dimensional parameters measured from traditional
49 methods in the field or in the lab (Bradley & Morris, 1990). 3D X-ray Computed Tomography
50 (CT) utilizes the penetrating capacity and attenuation of X-ray energy to image the 3D internal
51 structure and relative densities of materials ('phases') in a non-destructive manner (Cnudde &
52 Boone, 2013). The technique, developed for medical applications in the 1970s, soon led to the
53 higher resolution method X-ray Computed Microtomography (μ CT) in the 1980s and to the
54 study of microstructures in the geological and soil sciences (Ketcham and Carlson, 2001;
55 Ketcham, 2005; Carlson, 2006; Taina et al., 2008; Cnudde and Boone, 2013). In soil sciences,
56 the application of μ CT has largely focused on agricultural soils (Helliwell et al., 2013; Keller et
57 al., 2013; Menon et al., 2020; Mooney, 2002; Rogers & Benfey, 2015; Wildenschild &
58 Sheppard, 2013). By contrast, lacustrine, estuarine, glacial, fluvial and marine sediments and
59 associated soils typically represent multiple sediment sources, with mixing and superposition of
60 different minerogenic and biogenic components with variable water content (Bendle et al., 2015;
61 Dale et al., 2019; Griggs et al., 2015; Spagnolo et al., 2016; Spencer et al., 2017; Tarplee et al.,
62 2011; Voepel et al., 2019). This leads to significant textural and structural heterogeneities in
63 samples, which challenges the data acquisition and analysis approaches developed for the

64 examination of more homogenous agricultural soils. Here, we have focused on heterogeneous,
65 tidally flooded saltmarshes which retain both sedimentary (e.g. laminations) and pedological
66 (e.g., vegetation) features and are commonly referred to as soils. Therefore, for simplicity, we
67 use the term soils to include also unconsolidated and/or vegetated sediments deposited in aquatic
68 environments with minerogenic and biogenic components, as they present characteristics of both
69 sediments and soils.

70 The acquisition and interpretation of μ CT imagery of heterogeneous soils poses technical
71 challenges. Firstly, such soils are often unconsolidated and saturated, and therefore easily
72 disturbed, making recovery of ‘undisturbed’ samples very difficult, particularly at depth (Carr et
73 al., 2020). Secondly, samples with significant physical heterogeneity are challenging to
74 ‘segment’ into relevant phases based on X-ray attenuation coefficient alone. The segmentation
75 process is further complicated where there is a significant component of fine-grained sediments
76 below the spatial resolution of the scanning system (e.g. $<60\mu\text{m}$ in this study), whereby an
77 individual voxel in the reconstructed 3D volume represents the mean attenuation coefficient of
78 all elements present within. The intermediate grayscale value resulting from that mix of phases is
79 called the partial volume effect (Ketcham & Carlson, 2001); the more heterogenous and fine-
80 grained the material, the harder it becomes to isolate key phases based on their grayscale values
81 alone using global thresholding (Cnudde & Boone, 2013; Helliwell et al., 2013). Thirdly, most
82 soils, particularly those formed in aquatic environments such as wetland soils, contain variable
83 amounts of pore-water, meaning that the pore phase itself will be heterogeneous, with pores
84 being air-filled, water-filled, and often a combination of these states. Vegetated environments
85 such as coastal wetlands and saltmarshes also have significant heterogeneity in the belowground
86 organic phase: the structure and 3D deployment of roots within the soil vary depending on the

87 vegetation type. Furthermore, the roots' internal structure and density depend on their stage of
88 decay, which complicates the differentiation of live roots, necromass and pore space.

89 Significant advancements have been made to address the challenge of μ CT image segmentation
90 applied to heterogenous substrates, using more sophisticated "local adaptive" image processing
91 approaches such as gradient analysis and local-adaptive thresholding (Houston et al., 2013;
92 Ngom et al., 2011; Pot et al., 2020; Schlüter et al., 2010; Tarplee et al., 2011). Automated root
93 tracking algorithms have been developed to limit detection errors linked to the partial volume
94 effect ; however, they only detect root systems connected to the surface by user-specified seed
95 points, and might therefore miss buried root systems, which is a problem for soil carbon studies.
96 Another approach is to detect phase elements based on their 3D shapes rather than their
97 grayscale value, such as the tubular shape of roots using a Frangi filter (Frangi et al., 1998; Gao
98 et al., 2019; Schulz et al., 2013). These recent root detection methods give promising results, but
99 have so far been tested on sieved and repacked soils (Gao et al., 2019; Lucas et al., 2019), thus
100 eliminating the structural complexity of in situ soil systems and limiting our insight into soil
101 functions.

102 This study presents and evaluates a workflow for segmenting pores and organic phases in
103 complex heterogeneous, saturated sediment such as those found in coastal saltmarshes. Our
104 segmentation approach allows the user to quantify the interactions and complexity of both pores
105 and organic matter elements, and to distinguish the surface-connected live roots from the
106 necromass in order to get a complete picture of material interactions in heterogeneous soils. We
107 will discuss the potential applications of this approach to the study of key soil functions, such as
108 soil-plant interactions, soil structural stability against eroding forces, and soil carbon dynamics.

109

110 **2. Methods**

111

112 **2.1. Study site**

113 The site chosen to conduct this study, a saltmarsh in Tillingham, Blackwater Estuary, Essex, UK,

114 is representative of the heterogenous environments described above. Saltmarsh sediments are

115 typically formed of mixed fine-grained sediments (clays to medium sands) and biogenic

116 material, which makes them easily compacted and deformed during extraction. While

117 saltmarshes have a low vegetation diversity compared to nearby non-saline environments

118 (Teixeira et al., 2014), they are highly complex: tidal hydrology and strong vertical

119 physicochemical gradients mean that water content, plant survival rates, root to shoot ratio and

120 biomass accumulation vary in space and time (Moffett et al., 2012; Pezeshki & DeLaune, 2012).

121 In addition, the saltmarsh subsurface structure depends on tidally controlled sediment deposition,

122 but also on post-deposition processes such as autocompaction, bioturbation and root growth (De

123 Battisti et al., 2019; French, 2006; Turner, 2004). These characteristics mean that saltmarsh soils

124 are excellent candidates to test the robustness of our μ CT segmentation methods on challenging,

125 highly heterogeneous samples.

126 An upper saltmarsh sediment core (15 cm depth and 15 cm diameter) was collected in July 2018.

127 The vegetation cover at the sample location is dominated by Atriplex portulacoides (sea

128 purslane), Puccinellia maritima and Spartina anglica (Ford et al., 2016). The sediment type is

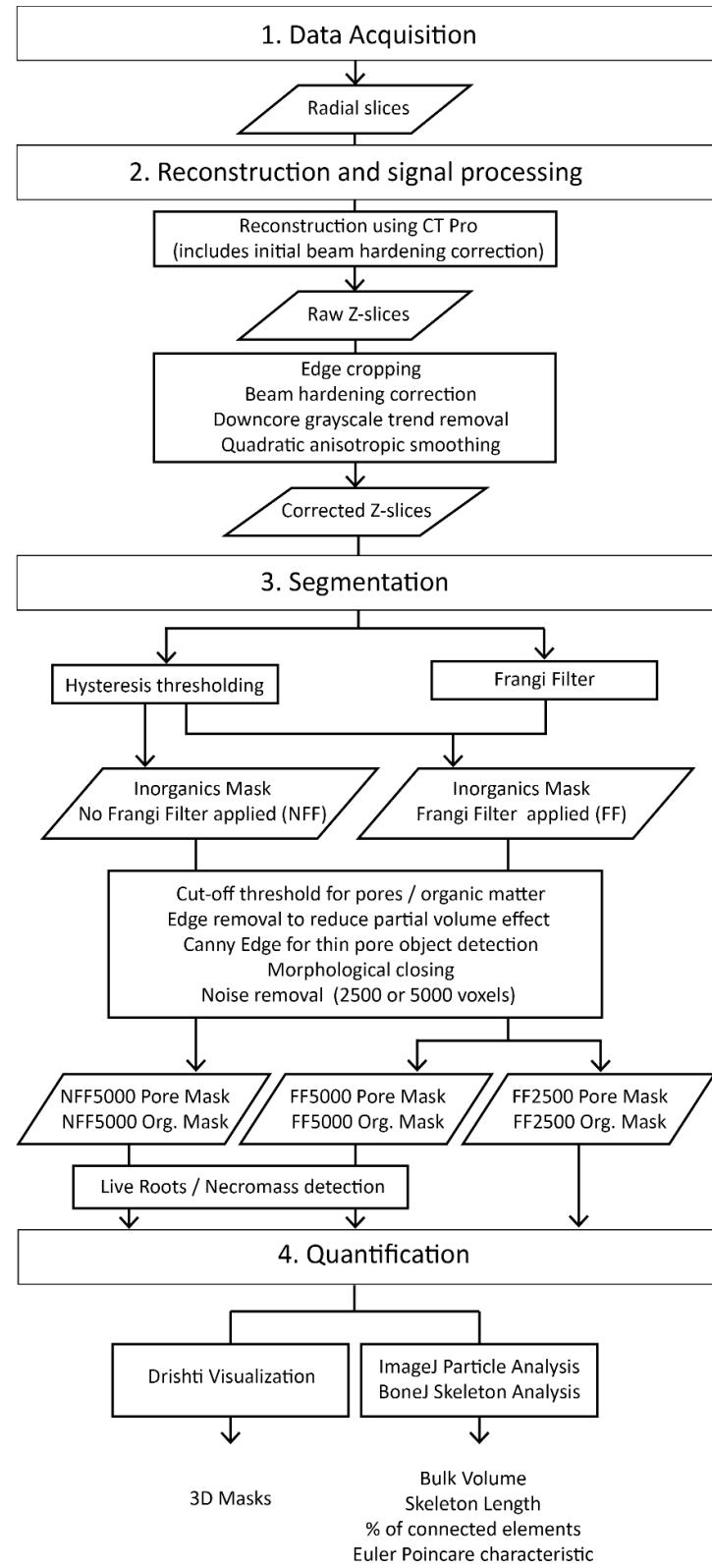
129 clay-dominated with a mean grain size of 69 μ m, with 71% of its material below 63 μ m. The

130 sediment core was collected using the advanced trimming method initially developed by

131 Hvorslev (1949): in brief, a plastic tube is placed on the soil surface; a trench is cut around the

132 tube, then carved into the shape of the core while the tube is lowered around the sample,
133 applying gentle constant pressure to limit edge drag and avoid compression and torque rotation.
134 Large roots are cut with scissors rather than a knife to avoid jostling, impact, twisting or other
135 deformation to the sediment inside the core. Fine fibrous roots are sawed through with a serrated
136 knife to avoid crushing and displacing the sediment around them. Further details and
137 justifications for the sampling method are provided by Carr et al. (2020). After extraction, the
138 core was stored upright in a cooling box filled with bubble wrap to minimize disturbance during
139 transport, and stored at 4 °C until required.

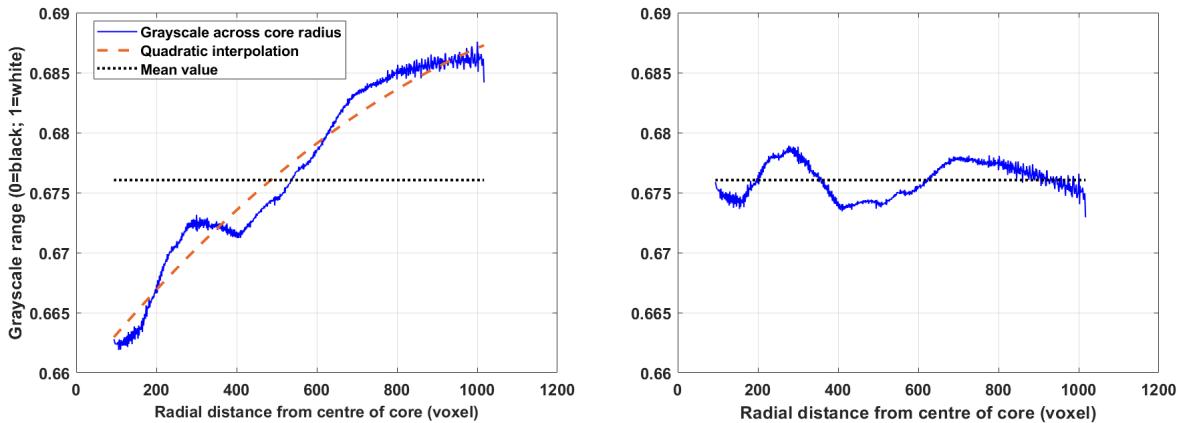
140 The core was scanned using a Nikon Metrology XT H 225 X-ray Computed Tomography (μ CT)
141 system at 205kV and 46μ A (9.4 W). The exposure time was 500ms at 36 dB gain. A Cu 1mm
142 copper filter was used to reduce beam hardening artefacts. 4486 projections were acquired with 4
143 frames per projection, for a scan time of 4.5 hours. The effective voxel size is 61.79μ m. The
144 voxel grid was then downscaled to 62.5μ m during volume reconstruction. The total volume
145 contains $2801*2783*2793$ voxels. Figure 1 summarizes the various steps applied to the scanned
146 volume. The different steps following scanning are detailed in the subsections below.



148 **Figure 1.** Data acquisition and processing workflow. The overall processing time from scanning
149 to obtention of output parameters is about four days on a high performance computing suite.

150 **2.2.Reconstruction and signal processing**

151 The volume reconstruction step was undertaken using Nikon's in-house software CT-Pro 3D
152 (Ray, 2011): the software finds the center of rotation of the raw X-ray projections and converts
153 the 2D radial slices into a 3D volumetric model defined by co-registered z-slices. The software
154 also partially corrects the z-slices for beam hardening using a polynomial fit: this imaging
155 artefact occurs when the X-ray beam becomes progressively attenuated as it penetrates from the
156 edge to the center of the sample, leading to an apparent darkening of the center and a brightening
157 of the edges (Ketcham & Carlson, 2001). This type of correction works when the overall matrix
158 can reasonably be assumed to have a consistent density throughout the sample (Ketcham &
159 Carlson, 2001), which should be the case for our clay-dominated material. Residual beam
160 hardening can still affect the segmentation phase, even when invisible to the naked eye. To
161 minimize its impact while removing edge disturbances during field sampling, an 8.75*8.75 cm
162 square mask was selected in the center of each z-slice as an area of interest and applied
163 throughout the volume (Fig. 1). A quadratic correction was then applied to the mean radial
164 grayscale, the grayscale value averaged vertically across the core and plotted against the radial
165 distance from the center (Fig. 2).

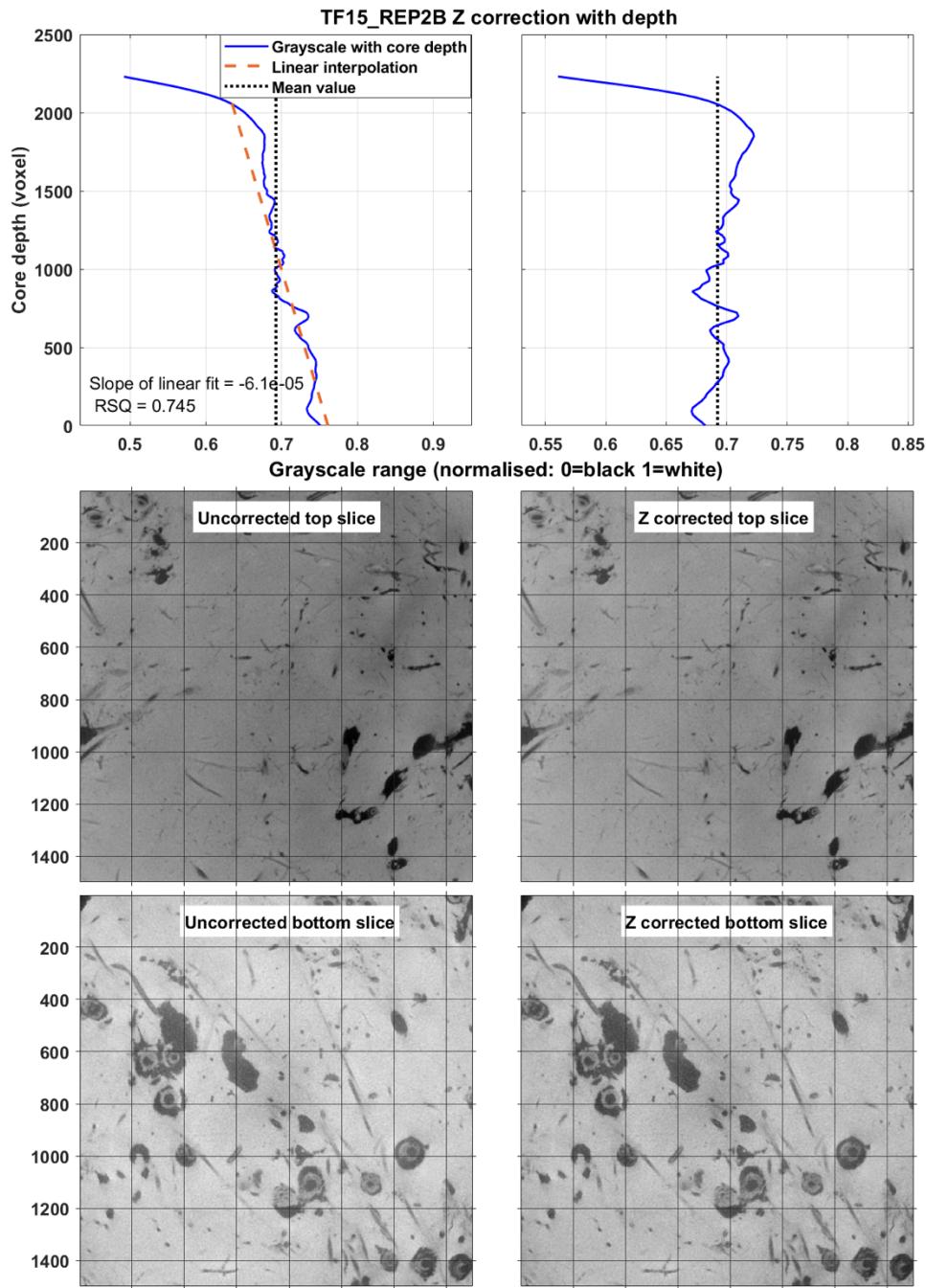


166

167 **Figure 2.** Correction of the residual beam hardening using a quadratic interpolation to remove
168 the overall trend of darker values at the center of the sample. The density variations that remain
169 in the detrended grayscale range correspond to actual density variations in the sample.

170 Compared to other soils where the material density is consistent throughout, another challenge of
171 clay-dominated coastal sediment is that they are highly compressible and may have rapid
172 sedimentation rates due to material brought in by the tide (French, 2006), leading to
173 autocompaction and to a downcore increase in the density of the inorganic phase. In our sample,
174 a linear trend in grayscale values is found with an R^2 value of 0.75 (Fig. 3); a lack of a similar
175 trend in the PVC tube around the sample (not shown) confirms that this trend is due to
176 autocompaction rather than an artefact of scanning. In order to more consistently distinguish the
177 mineral phase from the porosity and organic matter, this downcore trend is removed using a
178 linear interpolation (Fig. 3). In practice, this means smoothing out the microporosity through the
179 sample, which decreases with depth and affects the grayscale value of inorganic voxels due to
180 the partial volume effect. A shift remains at the top few centimeters of the sample, where the
181 trend is closer to a logarithmic fit in accordance with autocompaction patterns measured in silty
182 saltmarsh clay (Bartholdy et al., 2010). However, applying a logarithmic correction to the
183 topmost centimeters of the sample would excessively distort the grayscale value of the pores and

184 organic matter, which we can expect to find in greater quantity near the surface. This step
185 improves the segmentation of pores and roots in compressible sediment and soils, which is the
186 focus of this paper; however, analysis of the sediment phase should use the unmodified grayscale
187 values.



188

189 **Figure 3.** Removal of the autocompaction effect on grayscales using a downcore linear fit. The
190 correction factor at each z-slice is given by subtracting the linear fit from the uncorrected mean
191 grayscale then adding the mean grayscale of the whole core. The method does not remove the
192 logarithmic trend at the top of the sample so as to not excessively distort the grayscale values of
193 the pores and organic matter.

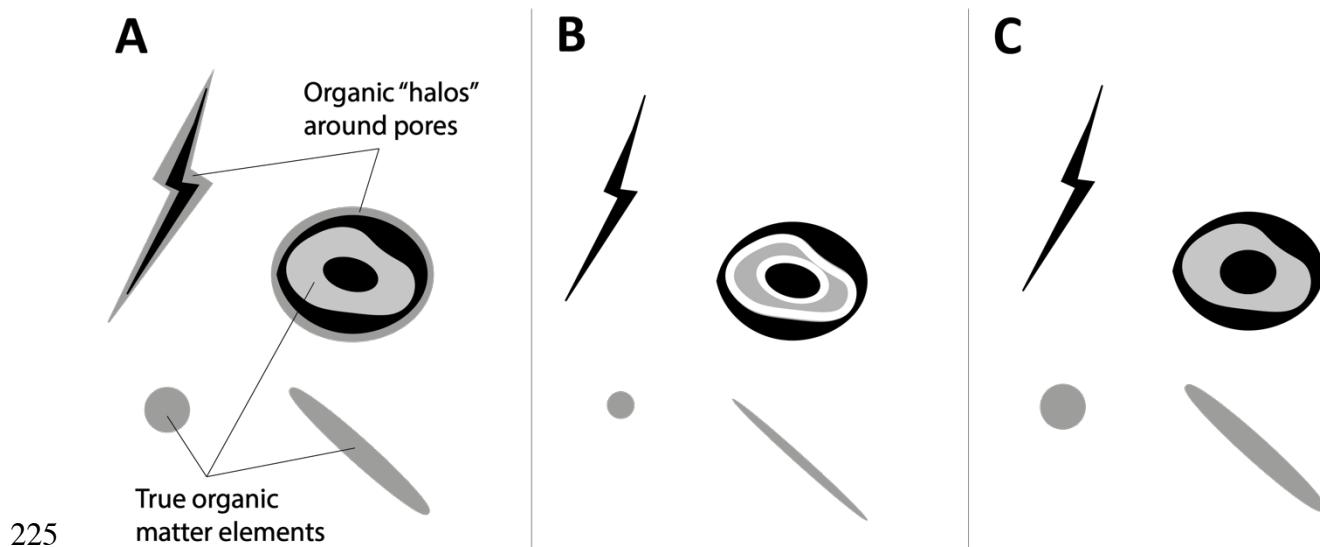
Finally, in order to reduce noise in the grayscale values while preserving the edges of the pores and organic features, different smoothing algorithms were tested using image filtering tools on Matlab, including Gaussian 3D filtering, 3D median filtering, guided image filtering and anisotropic diffusion (quadratic and exponential). The quadratic anisotropic diffusion tool *imdifusefilt* was found to be best suited for filtering out noise without losing the signal: the method enhances the contrast between matrix and darker elements by using strong gradients in the image as barriers to the smoothing effect and thus preserving the edges (Kaestner et al., 2006).

202 2.3.Segmentation

As stated in the introduction, μ CT data applied to heterogeneous fine grained substrates are challenging to segment into their constituting phases because the partial volume effect blurs the limit between phases (Cnudde and Boone, 2013), and are better served by a combination of local adaptive thresholding methods. We first applied a method called hysteresis thresholding to distinguish the high-density inorganics from pores and organic matter. This method considers two thresholds: voxels below the low threshold have a high likelihood of being part of a pore or organic element and are systematically segmented, while voxels below the high threshold are only segmented if they are connected to the low threshold elements. A Frangi filter was then

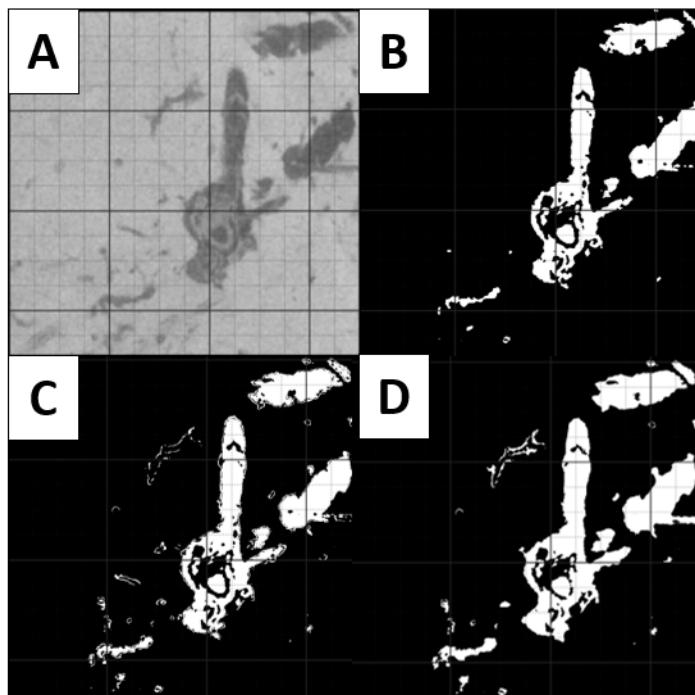
211 used to enhance tubular shapes within the sample by applying the Matlab function
212 *FrangiFilter3D* (Kroon, 2010). The Frangi method uses the orientation patterns (eigenvalues) of
213 the Hessian to distinguish tubular structures from plate-like or blob-like structures (Frangi et al.,
214 1998). The output binary masks from hysteresis thresholding and Frangi tubular shape
215 enhancement were combined, adopting a single threshold to separate pores from organic matter.

216 Additional steps were then added to improve the signal to noise ratio, including morphological
217 closing and the removal of partial volume effect artefacts, which can lead to the detection of
218 organic “halos” around pore elements. The outer edges of organic matter elements were
219 removed, then a dilation was performed to restore the remaining organic features to their original
220 size (Fig. 4). Finally, in the same way that root elements can have a low contrast with the
221 surrounding inorganic matrix but a characteristic tubular shape, thin cracks in the sediment can
222 have an intermediate grayscale value due to the partial volume effect, but a visible jagged edge.
223 To capture these remaining pore elements, we used a canny edge detection that detects both
224 strong edges and weak edges connected to strong edges (Canny, 1986) (Fig. 5).



225

226 **Figure 4.** Schematic diagram illustrating partial volume effect reduction using contour removal
227 (Matlab tool *bwmorph3*) followed by dilation (Matlab tool *imdilate*). Grey: Organic matter
228 elements. Black: Pores. A: Initial segmentation of pores and organic matter elements; the partial
229 volume effect causes organic “halos” to be detected around the pore elements. B: Remove edges
230 of the organic phase to erase “halos” from partial volume effect. C: Dilate remaining organic
231 matter elements back to their original size.



232
233 **Figure 5.** Application of a Canny edge filter to refine pore detection in the sample. A: Original
234 grayscale values. B: Pore segmentation without the Canny edge detection. C: Canny edge
235 detection applied to find the edges of pore elements (Young, 2014); notice how the canny edges
236 do not always connect with the features from B and add internal complexity to the pore phase. D:
237 Morphological closing applied to reconnect the pore features to their edges (Matlab tool
238 *imclose*).

239 In order to remove the noise detected by these various methods, we tested two noise thresholds:
240 2,500 voxels (0.61 mm³) and 5,000 voxels (1.22 mm³) (FF2500 and FF5000 respectively).
241 FF2500 contains 7,066 organic matter elements compared to 4,106 for FF5000 according to the
242 Matlab volumetric image processing function *bwconncomp*; this will significantly increase the
243 computational intensity of the quantification phase. Through visual comparison of the 3D
244 volumes for FF5000 and FF2500, and quantitative comparison of the percentages of pore and
245 organic fractions with depth, we tested whether this lower threshold significantly improves
246 signal detection, or whether the additional ~3,000 elements detected are noise elements with
247 little impact on the structure of the organic matter phase. We also tested whether the application
248 of a Frangi filter, which takes several hours to run, significantly changes the detection of the live
249 roots and necromass. To that end, a third version of the dataset NFF5000 was produced, using all
250 the previous steps except for the Frangi filter, and using a noise removal threshold of 5,000
251 voxels.

252 Traditional methods for distinguishing live from dead roots are based on color, shape and
253 plasticity ADDIN CSL_CITATION {"citationItems": [{"id": "ITEM-
254 1", "itemData": {"DOI": "10.1155/2012/217402", "author": [{"dropping-
255 particle": "", "family": "Persson", "given": "Hans A", "non-dropping-particle": "", "parse-
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257 Research", "id": "ITEM-1", "issued": {"date-parts": [[2012]]}, "title": "The High Input of Soil
258 Organic Matter from Dead Tree Fine Roots into the Forest Soil", "type": "article-
259 journal", "volume": "2012"}, "uris": [{"http://www.mendeley.com/documents/?uuid=4ccc3ad8-
260 7479-4f71-9f36-c206758f38fd"}], "mendeley": {"formattedCitation": "(Persson,
261 2012)", "plainTextFormattedCitation": "(Persson,

262 2012)"},"properties": {"noteIndex":0}, "schema": "https://github.com/citation-style-
263 language/schema/raw/master/csl-citation.json"}(Persson, 2012). However, color and plasticity
264 are not visible in μ CT images, and while live roots tend to be larger and better branched than
265 dead roots, densely grouped dead roots may be detected as one large, complex connected system;
266 using these traditional definitions would therefore be prone to errors. Instead, in the binary masks
267 NFF5000 and FF5000, we defined the live root system as all elements connected to the surface
268 layer, approximated by the top 80 voxels (= 5mm) of the sample. The remaining, unconnected
269 elements were classified as necromass.

270 **2.4. Quantification and ground referencing**

271 The 3D binary masks NFF5000, FF5000 and FF2500 were used for a detailed topological
272 analysis of the pores and organic matter elements using the automated software plugin BoneJ for
273 ImageJ (Doube et al., 2010; Schindelin et al., 2012). Morphological parameters (Table 2) were
274 extracted to determine how the different segmentation approaches affect the volume, length and
275 structural complexity of the pore and organic phases.

276 **Table 1.** List of morphological parameters considered.

Parameter	Unit	Definition
Total phase fraction	%	Fraction of the number of voxels belonging to a phase by the total number of voxels in each Z-slice and represented as depth profiles. The surface of the sample is automatically detected as the Z-slice wherein the proportion of matrix to void, segmented using an Otsu global thresholding, first reaches 75%.
Total volume	mm ³	Total volume of the studied phase
Total skeleton length	mm	Total length of the skeleton, obtained by shrinking a volume to a 1-voxel thick median structure, composed of nodes and branches that preserve the topological complexity of the initial volume.

Connectedness	%	Volume of the largest connected element divided by the total volume of the studied phase
Maximum Euler-Poincare characteristic	No unit	Topological invariant that describes the shape or structure of a topological space. In BoneJ, it is calculated as the number of objects minus the number of handles (hole that goes through an object) plus the number of cavities (holes enclosed within the object). It is used as a proxy for complexity and connectedness: negative values correspond to a well-connected complex system.

277

278 The 3D architecture of the sample was visualized using the volume rendering software Drishti
 279 (Limaye, 2012). In order to compare this 3D rendering with the actual sample, and check that the
 280 root and pore elements visible to the naked eye are correctly identified, the core was cut open
 281 with a serrated knife along a pre-marked section one day after scanning. Using a prior marking
 282 (either an incision in the PVC tube or a piece of metal, both of which will be visible in the X-ray
 283 attenuation coefficients), the equivalent vertical section was located in the segmented volume
 284 and overlain with a high-resolution photograph of the cut-off face. While there is no infallible
 285 way of cutting open a core without causing disturbance, the cohesive nature of the clay means
 286 that the largest pore structures and the position of the roots are likely to be preserved.

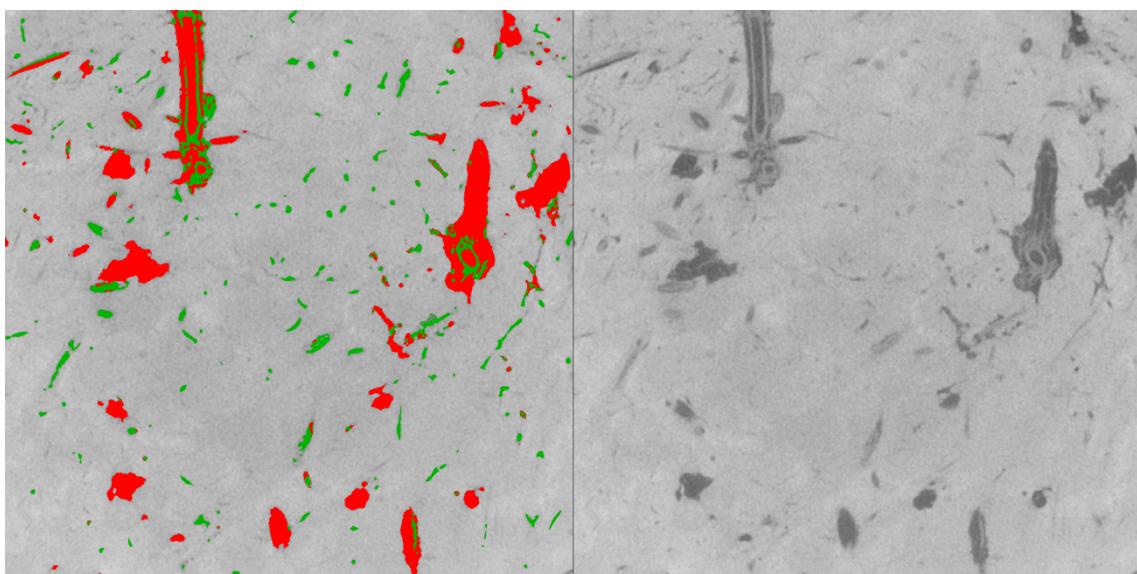
287 **3. Results**

288

289 **3.1.Quality control of the segmentation method**

290 Observation of the segmented horizontal slices provides insight into the different types of pores
 291 and organic matter elements detected by our segmentation method (Fig. 6). The larger organic
 292 elements have a complex inner structure with a hollow center and multiple other internal voids:
 293 these air spaces within roots and stems (aerenchyma) are an adaptation strategy of coastal
 294 wetland plants such as *Spartina* to anoxic conditions (Mitsch & Gosselink, 1986). The smaller,

295 tubular root elements visible in the Z-slice correspond either to lateral roots branching off from
296 the main *Spartina* root system, or to the roots of other plant species present on site such as
297 *Atriplex* or *Puccinellia*. The porosity elements appear either as tubular features, corresponding to
298 inner voids within roots and voids left behind by decaying roots, or as patches with no organic
299 origin.

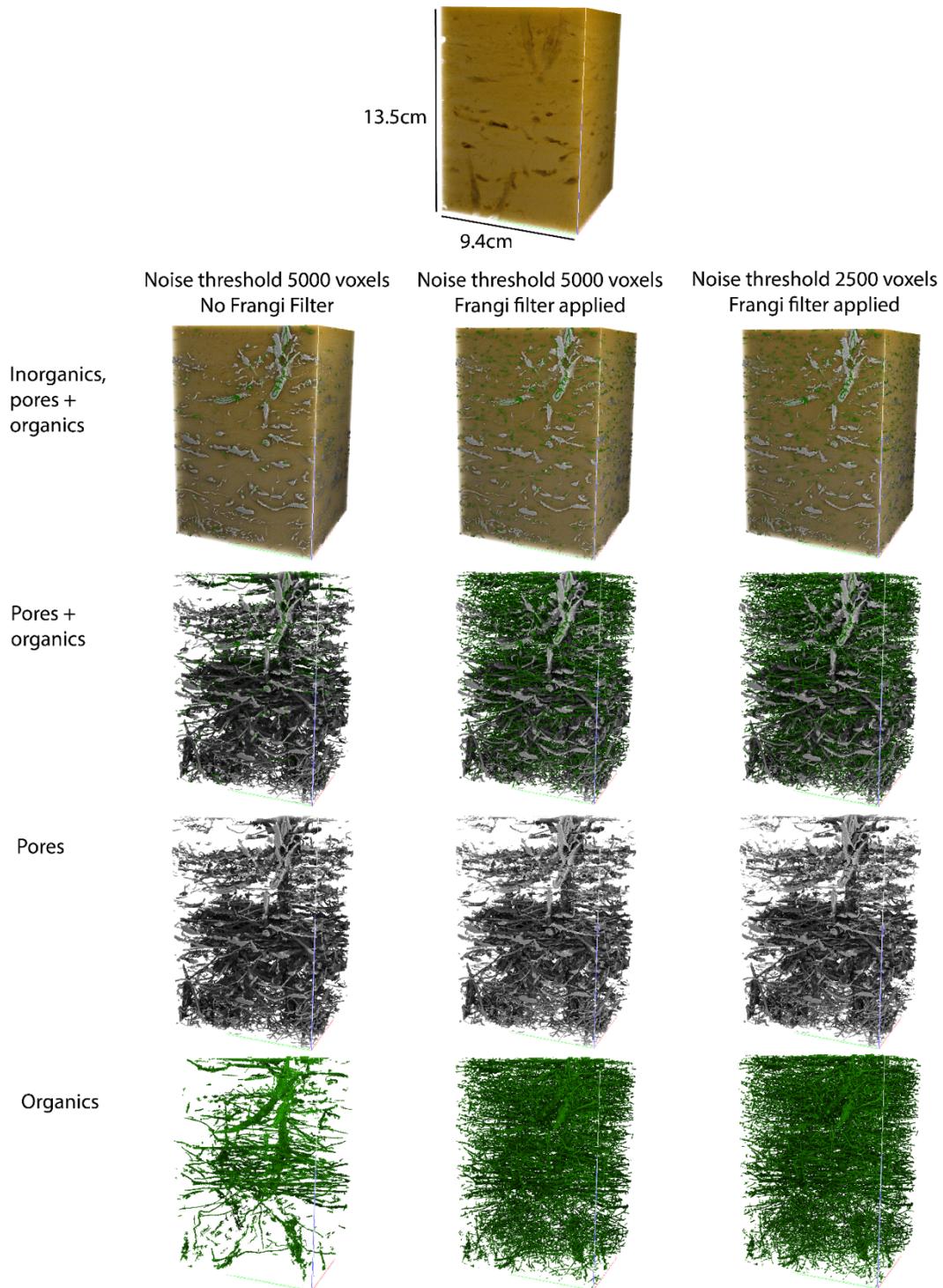


300

301 **Figure 6.** Segmentation example, showing the pore phase in red and the organic matter phase in
302 green overlain over the remaining inorganic phase.

303 Adding the Frangi filter had no visible effect on the detection of pore elements, but considerably
304 increased the size, extent and complexity of the organic matter phase (Fig. 7). At NFF5000 the
305 organic matter phase is limited to areas connected to large pores: because of the hysteresis
306 thresholding applied, medium grayscale voxels are only segmented if they are connected to a low
307 grayscale voxel. Therefore the Frangi filter is particularly efficient at detecting thin unconnected
308 root elements with no internal voids. By contrast, changing the noise removal threshold from

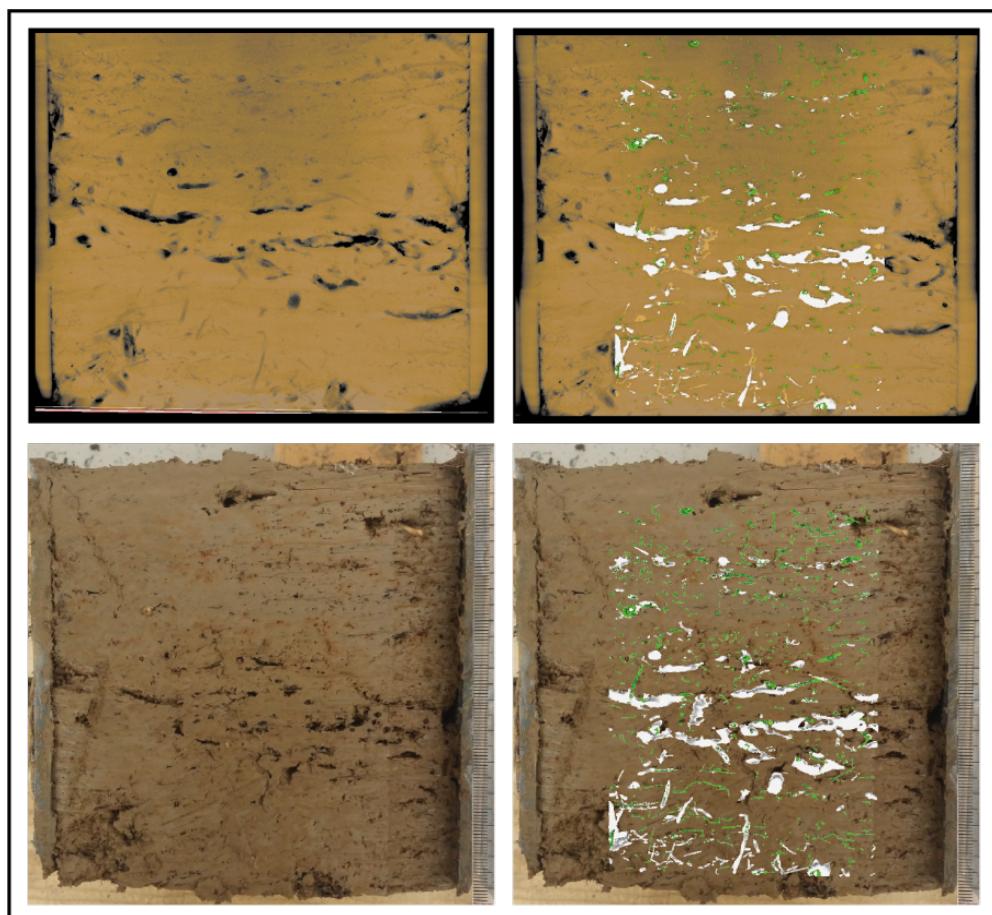
309 5,000 to 2,500 voxels had little visible impact on the 3D volumes of either the pore or the
310 organic matter phases (Fig. 7).



311

312 **Figure 7.** Segmented volume visualization using different segmentation methods and noise
313 thresholds. Grey = pores; green = organic matter; brown = inorganic matter. Volumes obtained
314 using Drishti (Limaye, 2012).

315 Ground referencing shows that the segmentation method proposed successfully distinguishes
316 areas dominated by roots from areas dominated by pores (Fig. 8). On the high resolution
317 photograph, the top half of the cut face (0-6 cm) is pockmarked by small roots, though individual
318 roots are difficult to visualize except for a few of the larger *Spartina* roots. The section between
319 6-12 cm contains more and larger porosity elements; the structure and distribution of these pores
320 are also similar to what is observed on the segmented volume.



321

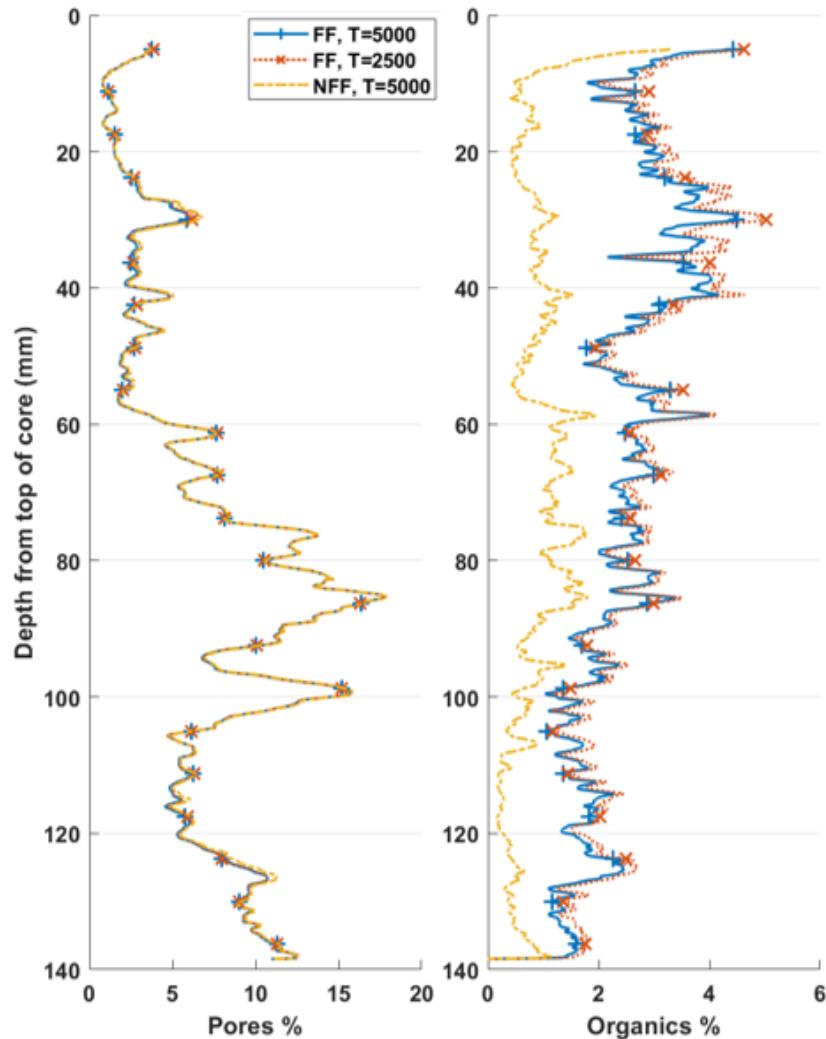
322 **Figure 8.** Ground referencing using the segmented volume overlain over a photograph of the
323 cut-off face of the core. On the segmented volume: brown = inorganic matter; grey = pores;
324 green = organic matter. Volume obtained using Drishti.

325 **3.2. Quantification and distinction between live roots and necromass**

326 The segmented pore phase can be separated into three regions: 0-6 cm, 6-10 cm and 10-14 cm.
327 The first region at 0-6 cm is characterized by a low pore fraction and bulk volume, a low
328 connectivity, but a peak in both the pores and organic matter' skeleton length (Fig. 9-10). This is
329 due to the influence of the *Spartina* stem and roots, which contain several transport pathways and
330 unconnected hollow chambers that add to the length of the overall pore system. The second
331 region at 6-10 cm sees a peak in the pore fraction (Fig. 9) and in the connectedness and
332 complexity of the pore system (Fig. 10). This region coincides with the branching off of the main
333 *Spartina* root into lateral roots at about 8 cm, and with a horizontal crack visible in the rendered
334 volume (Fig. 7). The root system may have preferentially developed within an area of structural
335 fragility and lesser density, as has been observed in previous studies (Lucas et al., 2019). The
336 third region sees a slight decrease in the bulk volume, connectedness and complexity of the pore
337 system (Fig. 9-10).

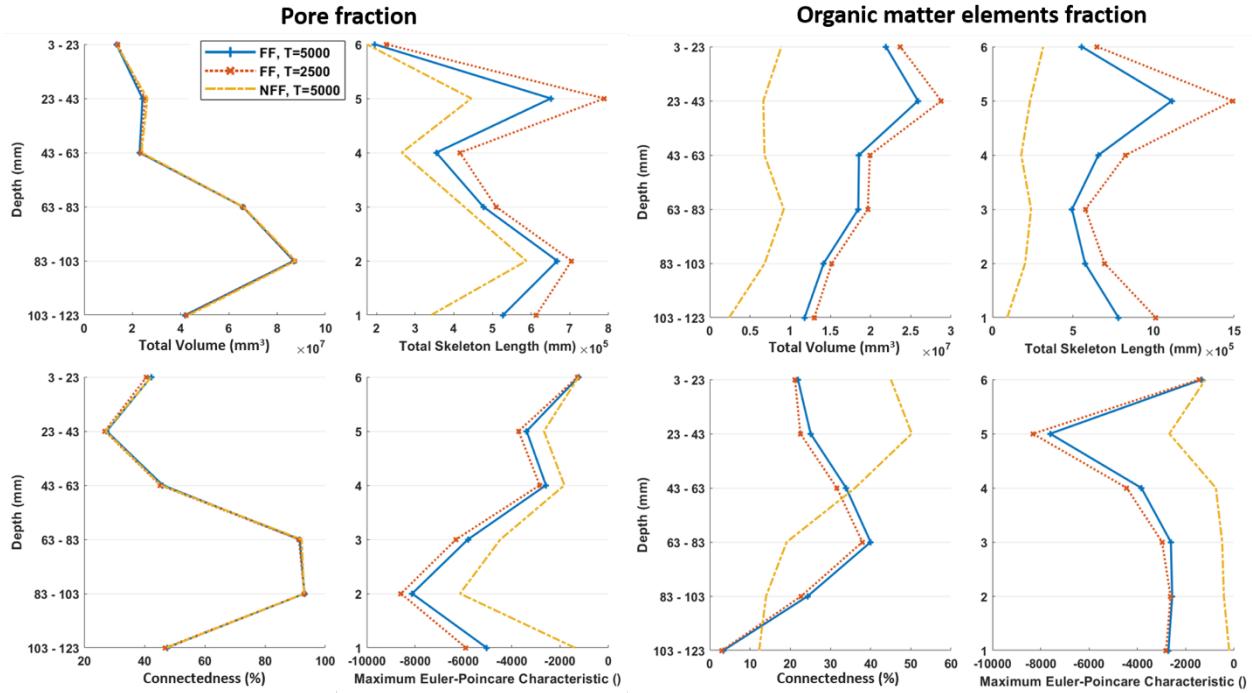
338 The organic matter phase is dense throughout the 15 cm sample (Fig. 7), which is to be expected
339 as we are still within the root zone of a biologically diverse upper saltmarsh: the saltmarsh root
340 zone extends from 15 to 50 cm depending on plant species and environmental conditions (De
341 Baets et al., 2008). The organic phase is denser in the first 5 centimeters then starts to decrease
342 downcore (Fig. 9). Adding the Frangi filter leads to the detection of a larger and more complex
343 organic matter phase overall, with a higher fraction, bulk volume and total skeleton length

344 detected at all depths (Fig. 9-10). Adding the Frangi filter also highlights the downcore decrease
345 of the organic fraction (Fig. 9), notably by detecting a higher number of elements not connected
346 to the main root system: in the first 5 cm of the sample, 25% of all segmented elements are
347 connected to the main root feature in FF5000 and FF2500, against 50% for NFF5000 (Fig. 10).



348

349 **Figure 9.** Depth profiles of the fractions of pores and of organic matter within the segmented
350 volume. FF: Frangi filter applied; NFF: No Frangi filter applied. T=5000: Noise threshold set at
351 5,000 voxels; T=2,500: Noise threshold set at 2,500 voxels.

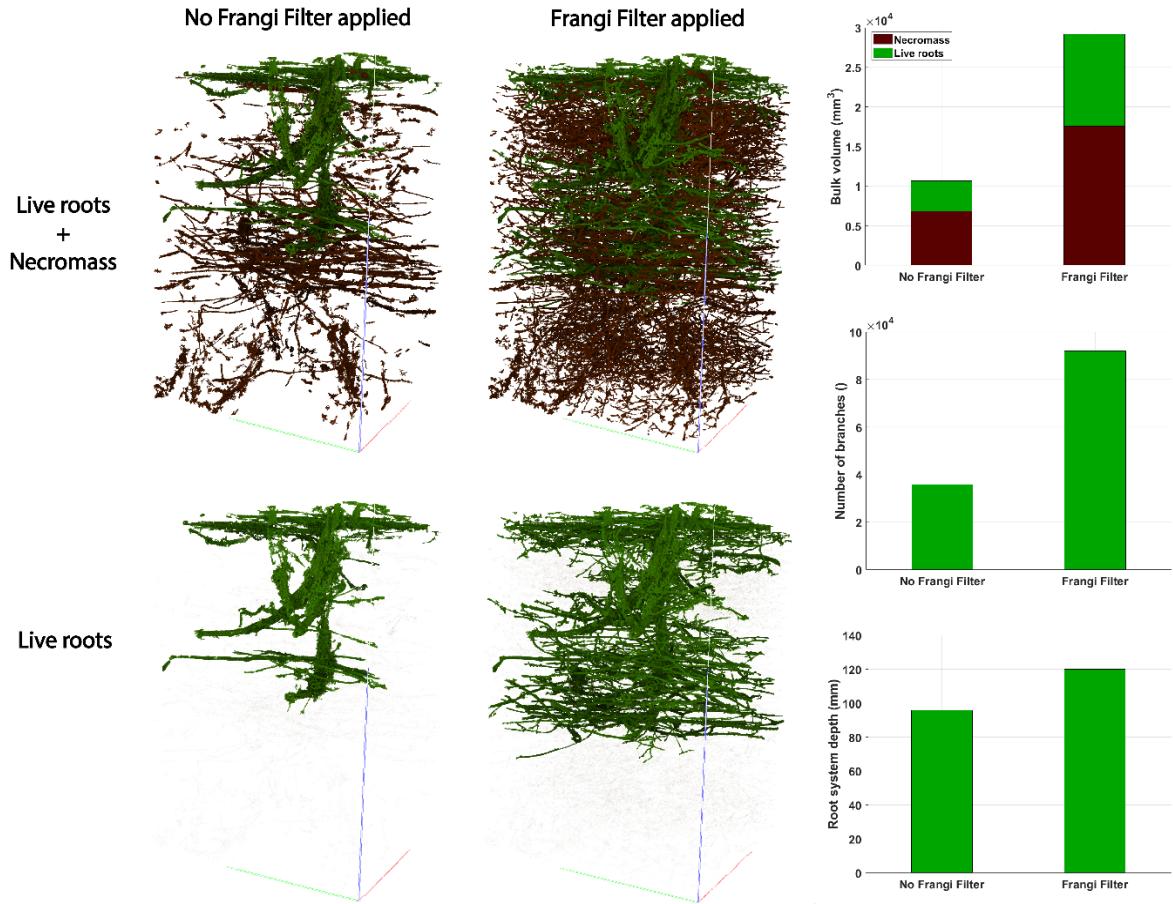


352

353 **Figure 10.** Topological analysis of pores and organic matter in 2-cm sections using BoneJ. ()

354 stands for no unit.

355 Figure 11 shows the potential of the Frangi filter to detect the necromass as well as the surface-
 356 connected live root system. The live root phase highlights one large *Spartina* root that branches
 357 out into smaller horizontal roots at about 80 mm depth. The live root system detected using the
 358 Frangi filter is larger and more complex, with a greater bulk volume and number of branches in
 359 the skeleton, and reaches 2.5cm deeper. A number of thin lateral roots also becomes apparent.
 360 Without the Frangi filter, by contrast, the live root system appears fragmented, and very little of
 361 the necromass is detected.



362

363 **Figure 11.** Effect of the Frangi filter on the extent, bulk volume, number of branches and root
 364 system depth of surface-connected “live” roots (green) and on the bulk volume of the necromass
 365 (dark red). The noise threshold is 5000 voxels.

366 4. Discussion

367 The use of μ CT in soil sciences allows us to visualize and quantify crucial structures and
 368 processes in the subsurface environment, but this technology presents ongoing challenges:
 369 sampling procedures to minimize sediment disturbance remain time-consuming, access to
 370 specialist X-ray μ CT scanning equipment is still not widespread in the soil science community,
 371 and the large datasets can create issues with processing and data storage. Finally, until standard

372 segmentation methods are widely agreed upon, interpretation of the μ CT volumes will require
373 specific expertise in 3D signal processing and image analysis. Therefore multidisciplinary
374 methodology papers are necessary to disseminate novel image processing techniques and
375 encourage the wider use of μ CT by soil scientists.

376 The approach outlined in this paper has multiple potential applications for soil science. The
377 three-phase segmentation (pores, organic matter elements, sediment matrix) allows the study of
378 pore-root interactions, something which has so far only been attempted in simplified conditions
379 such as sieved and repacked soil columns (Lucas et al., 2019). These interactions are expected to
380 play an important role in natural soil structure because of the high trait plasticity of roots: their
381 growth depends on the distribution of water, nutrients and of the areas of least resistance marked
382 by the porosity elements (Bardgett et al., 2014). At a higher resolution, the method could be used
383 to study the internal structure of plants and roots to visualize internal air spaces and infer nutrient
384 and fluid exchanges between the surface and subsurface: the presence of aerenchyma has been an
385 obstacle in previous segmentation attempts using a visual tracking algorithm . In addition, the
386 capacity of our method to distinguish live roots from the necromass opens the door for μ CT
387 applications to the study of soil structural stability. Indeed, roots can have either a weakening or
388 a stabilizing effect on the soil depending on their structure, connectedness and state of decay
389 (Brooks et al., 2020). Coarse roots can dislodge sediment and contribute to cliff-face erosion
390 (Feagin et al., 2009), while thinner and denser root meshes hold the soil together and provide a
391 physical barrier between the sediment and the water (Brooks et al., 2020; Gedan et al., 2011).
392 Decaying unconnected roots also contribute to making the soil less dense and more cohesive
393 (Brooks et al., 2020; Feagin et al., 2009).

Finally, the proposed method opens the door to the study of soil carbon dynamics and greenhouse gas exchanges in various types of soils. The potential of μ CT to model gas exchanges within 3D macropore structures is already known (van Marcke et al., 2010). Our approach can further the state of knowledge by providing a robust way of estimating root biomass. This should improve the estimation of carbon stocks since root systems and particularly the fine-root mass contribute disproportionately to soil carbon sequestration compared to the aboveground part of the plant (He et al., 2018). Root biomass estimation still lacks a methodological consensus (Addo-Danso et al., 2016), and traditional methods of belowground biomass estimation rely on labor-intensive and time-consuming destructive sampling protocols, as highlighted by Vialiale (2015): “This project became legendary as the most tedious task in our labs, tolerated only by everyone taking turns at the detailed and nearly endless staining, sorting, drying, and weighing protocols”. Furthermore, distinguishing live roots from necromass is recommended when estimating carbon sequestration potential in the soil (Adame et al., 2017). The proposed method, based on the connection of the root system to the surface, comes with its own limitations: the minimal size of roots detected depends on the scanning resolution chosen, and live root systems connected to shoots outside the perimeter of the core will be detected as necromass; prior knowledge of the live root thickness, internal structure and architecture is recommended to choose appropriate scanning parameters and to interpret the μ CT volumes. Nevertheless, owing to the capacity of μ CT to rapidly and non-destructively segment large and complex root systems, the method outlined in this paper could play a crucial role in studies of soil carbon dynamics.

415 **5. Conclusion**

416 This study applied X-ray Computed Microtomography to a highly heterogenous saltmarsh

417 sediment core. We developed a hybrid segmentation method that combines local adaptive

418 thresholding and shape detection to visualize and quantify the 3D distribution of pores, live roots

419 and necromass. The segmented volumes of roots and pores closely match the structures observed

420 on high-resolution photographs of the core taken along a cut-off face. We find that the use of a

421 Frangi filter for tubular structure enhancement is particularly efficient to highlight fine root

422 elements that have a low density contrast with the mineral phase. Compared with region-growth

423 segmentation methods, which only segment objects connected to pre-selected seed points, this

424 method is more versatile because it requires no prior knowledge of the core content, and because

425 it distinguishes between the live root system and the necromass. Our analysis of the pore and

426 organic matter elements' volume and structure shows clear interactions between the two phases:

427 root decay is a source of porosity in the sediment, while the presence of areas of lower density

428 with a higher concentration of pores determine where roots are able to develop. Our application

429 of X-ray μ CT has the potential to provide unprecedented knowledge of the 3D organisation of

430 pores and organic matter within heterogeneous soils, and to explore key ecosystem functioning

431 such as erodibility and carbon sequestration dynamics.

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443 **Author Contributions**

444 The manuscript was written through contributions of all authors. All authors have given approval
445 to the final version of the manuscript. Iris Moeller secured funding for the RESIST project and
446 defined our research objectives. Kate Spencer and Simon Carr developed an initial workflow for
447 X-ray μ CT application to saltmarsh soils. Clementine Chirol collected the sample with field
448 assistance from all authors, processed the dataset using an enhanced workflow and wrote the
449 article with edits from all authors.

450 **Notes**

451 The authors declare no competing financial interest.

452 **ACKNOWLEDGMENT**

453 We acknowledge funding from the National Environment Research Council (NERC) for the
454 research project RESIST(UK) (grant number XXX). We would like to thank the School of
455 Geography laboratory manager Michelle Day at Queen Mary University London for the use of
456 their Nikon Metrology XT H 225 X-ray Computed Tomography (μ CT) system.

457 **ABBREVIATIONS**

458 FF, frangi filter; NFF, no frangi filter; μ CT, computer microtomography

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